Model Based Development of Embedded Control Software

Part 1: Introduction

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Contents

Motivation

- What is an Embedded Control System?
- Traditional programming for control systems
- Model based development



Motivation - Cost

- Development
- Testing
- Integration
- Testing
- Validation
- Certification





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Motivation – Risk analysis

- Mean time between failures
- Failure cost in human lives/money
- Warranty/Insurance
- Fixing/Repairing possibility and costs







Embedded Control System

- Based on software that runs on computers (low powered)
- Interacts with physical world
- Software
 - derived from mathematical functions
 - execution takes non negligible time
 - Increasing complexity
- Consumes power that may be insufficient
- Reliability standards are very high



Embedded Software

- Timeliness
 - Requirements for real-time operations
 - Faster hardware does not solve all problems
- Concurrency
 - Software must react to multiple external stimuli
 - Threads/processes, semaphores, monitors, etc
 - Synchronous reactive languages (Esterel, Lustre)



Embedded Software

- Liveness
 - Software must not lock/crash/terminate
 - Predictable response
- Component technology
 - Interfaces/APIs
 - Libraries
 - OOP
 - Processes/Threads



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Embedded Software

- Heterogeneity
 - Mix of hardware and software designs
 - Handling of irregular or periodic events
 - Generalization and particularization of software, implementation language, programming techniques
- Reactivity
 - Respond to the environment at the speed of the environment
 - Real-time constraints, generally safety-critical
 - Adaptation to new requirements robustness
 - Concurrency analysis and smart compilers



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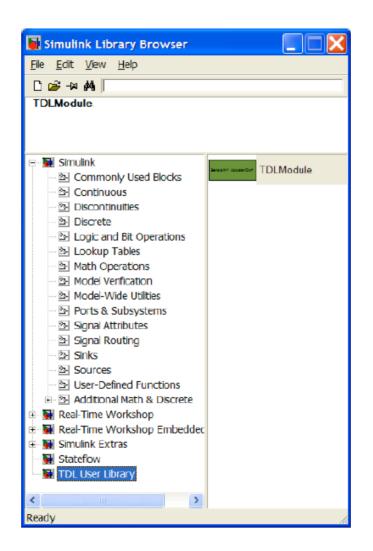
Traditional programming

- Manual coding for more than 90% of application code
- Highly platform dependent (HW + OS)
- Functionality code mixed with timing code
- Hardly reusable code
- High testing and integration costs
- Loss of "overall picture" after several development cycles



- Application development aided by visual tools (e.g., Matlab)
- Behavior specified via a model (i.e, pure mathematical, descriptive, etc)
- Simulation possible prior to full implementation (e.g., Simulink, Stateflow, etc)
- Shift of development resources from hard-core implementation to better design



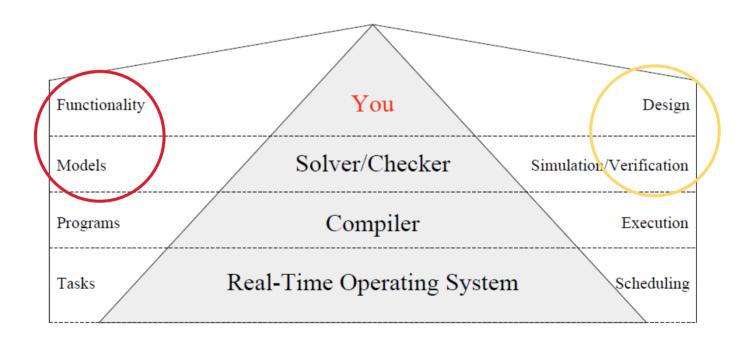




- Modular/component oriented design component frameworks, libraries
- Higher reusability factor
- Automatic code generation (e.g., Real-Time Workshop)
- Increased portability
- Shift from platform oriented to platform independent design



Embedded Software Engineering



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